

IN THE SPECIFICATION:

Please amend paragraph 50 of the specification as follows:

--[0050] According to the embodiment of FIG. 11, the platen 1106 is held parallel to the surface to be cleaned by a linkage 1129. The platen 1106 may be moved with respect to the housing 1101 by a lever 1130 through the linkage 1129. By moving the platen ~~stationary surface~~ 1106, the apparatus may be used on different surfaces (e.g., carpeting or rugs) and the cleaning ribbon 1103 may be more easily replaced. The manner shown in this embodiment is merely representative. A number of linkages or linkage-type devices could be used. Additionally, a number of means other than a hand-lever could be used to operate the linkage, including a foot-operated lever, or a motor, for example. If a motor is used, the raising and lowering of the platen 1106 may be done automatically by the apparatus 1100. By sensing the movement of the apparatus 1100 onto a new surface to be cleaned (e.g., movement from a hard floor to a carpet) the apparatus 1100 would automatically raise or lower the platen 1106 for uninterrupted cleaning on multiple surfaces. Such sensing of a new surface would be done, for example, by realizing a change in rolling resistance of the apparatus 1100 created by changing frictional characteristics of differing floor types.--